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APPLICATION NO.	FILING DATE	FIRST NAMED INVENTOR	ATTORNEY DOCKET NO.	CONFIRMATION NO.
09/782,552	02/13/2001	Hyun Soo Kang	8255.51US01	9696

23552 7590 04/30/2004

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EXAMINER
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WONG, ALLEN C

ART UNIT	PAPER NUMBER
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2613

DATE MAILED: 04/30/2004

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Please find below and/or attached an Office communication concerning this application or proceeding.

## Office Action Summary

**Application No.**

09/782,552

**Applicant(s)**

KANG ET AL.

**Examiner**

Allen Wong

**Art Unit**

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-- The MAILING DATE of this communication appears on the cover sheet with the correspondence address --

### Period for Reply

A SHORTENED STATUTORY PERIOD FOR REPLY IS SET TO EXPIRE 3 MONTH(S) FROM THE MAILING DATE OF THIS COMMUNICATION.

- Extensions of time may be available under the provisions of 37 CFR 1.136(a). In no event, however, may a reply be timely filed after SIX (6) MONTHS from the mailing date of this communication.
- If the period for reply specified above is less than thirty (30) days, a reply within the statutory minimum of thirty (30) days will be considered timely.
- If NO period for reply is specified above, the maximum statutory period will apply and will expire SIX (6) MONTHS from the mailing date of this communication.
- Failure to reply within the set or extended period for reply will, by statute, cause the application to become ABANDONED (35 U.S.C. § 133). Any reply received by the Office later than three months after the mailing date of this communication, even if timely filed, may reduce any earned patent term adjustment. See 37 CFR 1.704(b).

### Status

- 1) ☐ Responsive to communication(s) filed on \_\_\_\_.
- 2a) ☐ This action is **FINAL**. 2b) ☒ This action is non-final.
- 3) ☐ Since this application is in condition for allowance except for formal matters, prosecution as to the merits is closed in accordance with the practice under *Ex parte Quayle*, 1935 C.D. 11, 453 O.G. 213.

### Disposition of Claims

- 4) ☒ Claim(s) 1-12 is/are pending in the application.
- 4a) Of the above claim(s) \_\_\_\_ is/are withdrawn from consideration.
- 5) ☐ Claim(s) \_\_\_\_ is/are allowed.
- 6) ☒ Claim(s) 1-12 is/are rejected.
- 7) ☐ Claim(s) \_\_\_\_ is/are objected to.
- 8) ☐ Claim(s) \_\_\_\_ are subject to restriction and/or election requirement.

### Application Papers

- 9) ☐ The specification is objected to by the Examiner.
- 10) ☐ The drawing(s) filed on \_\_\_\_ is/are: a) ☐ accepted or b) ☐ objected to by the Examiner.  
Applicant may not request that any objection to the drawing(s) be held in abeyance. See 37 CFR 1.85(a).  
Replacement drawing sheet(s) including the correction is required if the drawing(s) is objected to. See 37 CFR 1.121(d).
- 11) ☐ The oath or declaration is objected to by the Examiner. Note the attached Office Action or form PTO-152.

### Priority under 35 U.S.C. § 119

- 12) ☒ Acknowledgment is made of a claim for foreign priority under 35 U.S.C. § 119(a)-(d) or (f).
- a) ☒ All b) ☐ Some \* c) ☐ None of:
- 1) ☒ Certified copies of the priority documents have been received.
  - 2) ☐ Certified copies of the priority documents have been received in Application No. \_\_\_\_.
  - 3) ☐ Copies of the certified copies of the priority documents have been received in this National Stage application from the International Bureau (PCT Rule 17.2(a)).
- \* See the attached detailed Office action for a list of the certified copies not received.

### Attachment(s)

- |  |   |
|--|---|
| 1) <input checked="" type="checkbox"/> Notice of References Cited (PTO-892)  | 4) <input type="checkbox"/> Interview Summary (PTO-413)<br>Paper No(s)/Mail Date. ____. |
| 2) <input type="checkbox"/> Notice of Draftsperson's Patent Drawing Review (PTO-948)   | 5) <input type="checkbox"/> Notice of Informal Patent Application (PTO-152)             |
| 3) <input checked="" type="checkbox"/> Information Disclosure Statement(s) (PTO-1449 or PTO/SB/08)<br>Paper No(s)/Mail Date <u>4.6</u> . | 6) <input type="checkbox"/> Other: ____.  |

## **DETAILED ACTION**

### ***Claim Objections***

1. Claims 2, 3, 10 and 11 are objected to because of the following informalities: In line 5 of claim 2, after "equation 1", the period "." should be replaced with a colon ":". In line 5 of claim 3, after "equation 2", the period "." should be replaced with a colon ":". In line 6 of claim 10, after "equation 1", the period "." should be replaced with a colon ":". In line 6 of claim 11, after "equation 2", the period "." should be replaced with a colon ":". Appropriate correction is required.

### ***Claim Rejections - 35 USC § 102***

1. The following is a quotation of the appropriate paragraphs of 35 U.S.C. 102 that form the basis for the rejections under this section made in this Office action:

A person shall be entitled to a patent unless –

(e) the invention was described in a patent granted on an application for patent by another filed in the United States before the invention thereof by the applicant for patent, or on an international application by another who has fulfilled the requirements of paragraphs (1), (2), and (4) of section 371(c) of this title before the invention thereof by the applicant for patent.

The changes made to 35 U.S.C. 102(e) by the American Inventors Protection Act of 1999 (AIPA) and the Intellectual Property and High Technology Technical Amendments Act of 2002 do not apply when the reference is a U.S. patent resulting directly or indirectly from an international application filed before November 29, 2000. Therefore, the prior art date of the reference is determined under 35 U.S.C. 102(e) prior to the amendment by the AIPA (pre-AIPA 35 U.S.C. 102(e)).

2. Claims 1 and 5 are rejected under 35 U.S.C. 102(e) as being anticipated by Hatano (6,091,460).

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Regarding claim 1, Hatano discloses a motion vector estimation method comprising the steps of:

a) obtaining a predicted motion vector on the basis of motion vectors of blocks surrounding a block to be currently coded (fig.11, element 3a produces predicted image motion vector 110 from the motion vector of blocks being previously stored in memory 16);

b) searching for a motion vector with a minimum motion compensated error and, meanwhile, obtaining the minimum motion compensated error, a motion compensated error of a zero vector and a motion compensated error of said predicted motion vector (fig.11, element 3a searches for motion vector with the least amount of error or distortion and col.25, ln.35-62 discloses obtaining the motion compensated errors and the minimum errors);

c) comparing said motion compensated error of said zero vector with a first predetermined threshold value (fig.10, element 7b);

d) determining said zero vector as a final motion vector if it is determined at said step c) that said motion compensated error of said zero vector is smaller than said first predetermined threshold value (col.25, ln.35-62 and fig.11, note elements 7f and 7b are taken into consideration to see if the zero vector motion compensated error is smaller than the threshold value, and thus element 4c will output the final motion vector);

e) comparing said motion compensated error of said predicted motion vector with a second predetermined threshold value if it is determined at said step c) that said

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motion compensated error of said zero vector is not smaller than said first predetermined threshold value (col.25, ln.35-62 and fig.11, note elements 7f and 7b are taken into consideration to compare values if the zero vector motion compensated error is not smaller than the threshold value, and thus element 4c will output the final motion vector);

f) determining said predicted motion vector as said final motion vector if it is determined at said step e) that said motion compensated error of said predicted motion vector is smaller than said second predetermined threshold value (col.25, ln.35-62 and fig.11, note elements 7f and 7b are taken into consideration to compare values if the zero vector motion compensated error is not smaller than the threshold value, and thus element 4c will output the final motion vector); and

g) determining said motion vector with the minimum motion compensated error as said final motion vector if it is determined at said step e) that said motion compensated error of said predicted motion vector is not smaller than said second predetermined threshold value (col.25, ln.35-62 and fig.11, note elements 7f and 7b are taken into consideration to compare values if the zero vector motion compensated error is not smaller than the threshold value, and thus element 4c will output the final motion vector).

Note claims 8-9 have similar corresponding elements.

Regarding claims 4 and 12, Hatano discloses the use of a full search method (fig.11, note all of the candidate motion vectors are sent into element 3a).

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Regarding claim 5, Hatano discloses a motion vector estimation device comprising:

a motion vector predictor for obtaining a predicted motion vector on the basis of motion vectors of blocks surrounding a block to be currently coded, stored in a motion vector memory (fig.11, element 3a produces predicted image motion vector 110 from the motion vector of blocks being previously stored in memory 16);

a motion vector searcher for searching for a motion vector with a minimum motion compensated error using a current frame and a reference frame and, meanwhile, obtaining the minimum motion compensated error, a motion compensated error of a zero vector and a motion compensated error of said predicted motion vector (fig.11, element 3a searches for motion vector with the least amount of error or distortion and col.25, ln.35-62 discloses obtaining the motion compensated errors and the minimum errors);

a motion vector selector for receiving said motion vector with the minimum motion compensated error, said minimum motion compensated error, said motion compensated error of said zero vector and said motion compensated error of said predicted motion vector from said motion vector searcher, said predicted motion vector from said motion vector predictor and first and second threshold values and then determining a final motion vector using the received information (fig.11, element 4c is the motion vector selector; and in col.25, ln.35-62 and fig.11, note elements 7f and 7b are taken into consideration to compare values if the zero vector

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motion compensated error is not smaller than the threshold value, and thus element 4c will selectively output the final motion vector); and

said motion vector memory adapted to receive and store the final motion vector determined by said motion vector selector (fig.11, element 16 and also note the fig.16, element 17b is the motion compensation prediction circuit that has an output that goes to memory element 16).

Regarding claim 6, Hatano discloses the first motion compensated error calculator (fig.11, element 5a) and the second motion compensated error calculator (fig.11, element 5b).

Regarding claim 7, Hatano discloses the first comparator (fig.11, element 7e), the second comparator (fig.11, element 7f), the first switch (fig.11, element 4c) and the second switch (fig.11, element 4d).

### ***Claim Rejections - 35 USC § 103***

3. The following is a quotation of 35 U.S.C. 103(a) which forms the basis for all obviousness rejections set forth in this Office action:

(a) A patent may not be obtained though the invention is not identically disclosed or described as set forth in section 102 of this title, if the differences between the subject matter sought to be patented and the prior art are such that the subject matter as a whole would have been obvious at the time the invention was made to a person having ordinary skill in the art to which said subject matter pertains. Patentability shall not be negated by the manner in which the invention was made.

4. Claims 2 and 10 are rejected under 35 U.S.C. 103(a) as being unpatentable over Hatano (6,091,460) in view of Eifrig (6,005,980).

Hatano discloses motion vector estimation (fig.11). Hatano fails to disclose the determination of a median value of motion vectors using the equation  $MVP = MED(MV1,$

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*MV2, MV3*). However, Eifrig teaches determination of a median value of motion vectors using the equation  $MVP = MED(MV1, MV2, MV3)$  (col.14, ln.4-9). Therefore, it would have been obvious to one of ordinary skill in the art to incorporate the teachings of Hatano and Eifrig for accurately coding image data so as to efficiently process high quality image display (Eifrig col.2, ln.16-17).

Claims 3 and 11 are rejected under 35 U.S.C. 103(a) as being unpatentable over Hatano (6,091,460) in view of Sun (6,014,181).

Hatano discloses the calculation of the sum of squares of differences or the SAD (col.28, ln.12-30). Hatano does not specifically disclose the equation for calculating the SAD in the manner as described in claims 3 and 11. However, Sun teaches the calculation of the SAD (col.2, ln.24-40; note the equation is similar to the equation disclosed in claims 3 and 11 where the limits of *i* and *j* are from 0 to 15, and that one can manipulate the equation shown in Sun to obtain the equation in the claims). Therefore, it would have been obvious to one of ordinary skill in the art to combine the teachings of Hatano and Sun for obtaining the equation to calculate the well known concept of a sum of absolute differences so as to accurately, efficiently estimate motion information in image data in a robust, precise manner (col.2, ln.17-21).

#### **Contact Information**

Any inquiry concerning this communication or earlier communications from the examiner should be directed to Allen Wong whose telephone number is (703) 306-5978. The examiner can normally be reached on Mondays to Thursdays from 8am-6pm.




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If attempts to reach the examiner by telephone are unsuccessful, the examiner's supervisor, Christopher Kelley can be reached on (703) 305-4856. The fax phone number for the organization where this application or proceeding is assigned is 703-872-9306.

Information regarding the status of an application may be obtained from the Patent Application Information Retrieval (PAIR) system. Status information for published applications may be obtained from either Private PAIR or Public PAIR. Status information for unpublished applications is available through Private PAIR only. For more information about the PAIR system, see <http://pair-direct.uspto.gov>. Should you have questions on access to the Private PAIR system, contact the Electronic Business Center (EBC) at 866-217-9197 (toll-free).

Allen Wong  
Examiner  
Art Unit 2613

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4/27/04

  
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